Syllabus
for
Mechanical Engineering
(MTQP07)

Note:
- i.   **The Question Paper which will have 75 questions.**
- ii. **All questions will be based on Subject-Specific Knowledge.**
- iii. **All questions are compulsory.**
- iv. **The Question paper will be in English.**

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Unit 1: Engineering Mathematics

Linear Algebra: Matrix Algebra, Systems of linear equations, Eigenvalues, Eigenvectors.

Calculus: Mean value theorems, Theorems of integral calculus, Evaluation of definite and improper integrals, Partial Derivatives, Maxima and minima, Multiple integrals, Fourier series, Vector identities, Directional derivatives, Line integral, Surface integral, Volume integral, Stokes's theorem, Gauss's theorem, Divergence theorem, Green's theorem.

Differential equations: First order equations (linear and nonlinear), Higher order linear differential equations with constant coefficients, Method of variation of parameters, Cauchy's equation, Euler's equation, Initial and boundary value problems, Partial Differential Equations, Method of separation of variables.

Complex variables: Analytic functions, Cauchy's integral theorem, Cauchy's integral formula, Taylor series, Laurent series, Residue theorem, Solution integrals.

Probability and Statistics: Sampling theorems, Conditional probability, Mean, Median, Mode, Standard Deviation, Random variables, Discrete and Continuous distributions, Poisson distribution, Normal distribution, Binomial distribution, Correlation analysis, Regression analysis

Numerical Methods: Matrix inversion, solutions of non-linear algebraic equations, iterative methods for solving differential equations, numerical integration, regression and correlation analysis.

Unit 2: Applied Mechanics and Design

Engineering Mechanics: Free-body diagrams and equilibrium; friction and its applications including rolling friction, belt-pulley, brakes, clutches, screw jack, wedge, vehicles, etc.; trusses and frames; virtual work; kinematics and dynamics of rigid bodies in plane motion; impulse and momentum (linear and angular) and energy formulations; Lagrange's equation.

Mechanics of Materials: Stress and strain, elastic constants, Poisson's ratio; Mohr's circle for plane stress and plane strain; thin cylinders; shear force and bending moment diagrams; bending and shear stresses; concept of shear centre; deflection of beams; torsion of circular shafts; Euler's theory of

columns; energy methods; thermal stresses; strain gauges and rosettes; testing of materials with universal testing machine; testing of hardness and impact strength.

Theory of Machines: Displacement, velocity and acceleration analysis of plane mechanisms; dynamic analysis of linkages; cams; gears and gear trains; flywheels and governors; balancing of reciprocating and rotating masses; gyroscope.

Vibrations: Free and forced vibration of single degree of freedom systems, effect of damping; vibration isolation; resonance; critical speeds of shafts

Machine Design: Design for static and dynamic loading; failure theories; fatigue strength and the SN diagram; principles of the design of machine elements such as bolted, riveted and welded joints; shafts, gears, rolling and sliding contact bearings, brakes and clutches, springs

Unit 3: Fluid Mechanics and Thermal Sciences

Fluid Mechanics: Fluid properties; fluid statics, forces on submerged bodies, stability of floating bodies; control-volume analysis of mass, momentum and energy; fluid acceleration; differential equations of continuity and momentum; Bernoulli's equation; dimensional analysis; viscous flow of incompressible fluids, boundary layer, elementary turbulent flow, flow through pipes, head losses in pipes, bends and fittings; basics of compressible fluid flow.

Heat-Transfer: Modes of heat transfer; one dimensional heat conduction, resistance concept and electrical analogy, heat transfer through fins; unsteady heat conduction, lumped parameter system, Heisler's charts; thermal boundary layer, dimensionless parameters in free and forced convective heat transfer, heat transfer correlations for flow over flat plates and through pipes, effect of turbulence; heat exchanger performance, LMTD and NTU methods; radiative heat transfer, Stefan- Boltzmann law, Wien's displacement law, black and grey surfaces, view factors, radiation network analysis.

Thermodynamics: Thermodynamic systems and processes; properties of pure substances, behaviour of ideal and real gases; zeroth and first laws of thermodynamics, calculation of work and heat in various processes; second law of thermodynamics; thermodynamic property charts and tables, availability and irreversibility; thermodynamic relations.

Applications: *Power Engineering*: Air and gas compressors; vapour and gas power cycles, concepts of regeneration and reheat. *I.C. Engines*: Air-standard Otto, Diesel and dual cycles. *Refrigeration and air-conditioning*: Vapour and gas refrigeration and heat pump cycles; properties of moist air, psychrometric chart, basic psychrometric processes. *Turbomachinery*: Impulse and reaction principles, velocity diagrams, Pelton-wheel, Francis and Kaplan turbines; steam and gas turbines.

Unit 4: Materials, Manufacturing and Industrial Engineering

Engineering Materials: Structure and properties of engineering materials, phase diagrams, heat treatment, stress-strain diagrams for engineering materials.

Casting, Forming and Joining Processes: Different types of castings, design of patterns, moulds and cores; solidification and cooling; riser and gating design. Plastic deformation and yield criteria; fundamentals of hot and cold working processes; load estimation for bulk (forging, rolling, extrusion, drawing) and sheet (shearing, deep drawing, bending) metal forming processes; principles of powder metallurgy. Principles of welding, brazing, soldering and adhesive bonding.

Machining and Machine Tool Operations: Mechanics of machining; basic machine tools; single and multi-point cutting tools, tool geometry and materials, tool life and wear; economics of machining; principles of non-traditional machining processes; principles of work holding, jigs and fixtures; abrasive machining processes; NC/CNC machines and CNC programming.

Metrology and Inspection: Limits, fits and tolerances; linear and angular measurements; comparators; interferometry; form and finish measurement; alignment and testing methods; tolerance analysis in manufacturing and assembly; concepts of coordinate-measuring machine (CMM).

Computer Integrated Manufacturing: Basic concepts of CAD/CAM and their integration tools; additive manufacturing.

Production Planning and Control: Forecasting models, aggregate production planning, scheduling, materials requirement planning; lean manufacturing.

Inventory Control: Deterministic models; safety stock inventory control systems.

Operations Research: Linear programming, simplex method, transportation, assignment, network flow models, simple queuing models, PERT and CPM.

Unit 5: Mechatronics and Industrial Robotics

Sensors and Drives: Sensor characteristics, different types of sensors and transducers, micro sensors, electrical contacts, actuators, and switches, signal processing devices; relays, output devices. Drives: Electrical, Mechanical, Hydraulic & Pneumatic. Automatic Production and Assembly Machines: Transfer lines, Production and throughput, Buffer Storage

Robot Kinematics & Gripper Mechanism : Role of robotics in automated manufacturing system, Robot anatomy. Robot classifications and specifications, Manipulation and Control. Robot kinematics, forward and reverse transformation, homogeneous transformations. Fundamental Rotation matrices, Kinematic modeling of the manipulator, Denavit-Hartenberg Notation.

Robot Manipulators, Actuators and Drives : Robot vision and their interfaces, Machine Vision Applications. Welding, spray painting and finish coating, Parts Mating & Parts Joining Operations. Types of Robot Manipulators, Application of Robot Manipulators, Construction of a Robot Manipulatotor.

Robot Sensors and Robot Safety: Sensors in Robotics, classification of Robotic sensors, Acoustic sensors Optical Sensors, Pneumatic Sensors. Touch Sensors, Force Sensors, Force Sensing Wrist and its applications. Robot Planning and Installation, Robot Safety, Need of Robot Safety

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